

Lecture 9 - February 7

Model Checking

Examples: LTS Formulation

Paths, Unwinding All Possible Paths

Path Satisfaction: X, G, F

Announcements

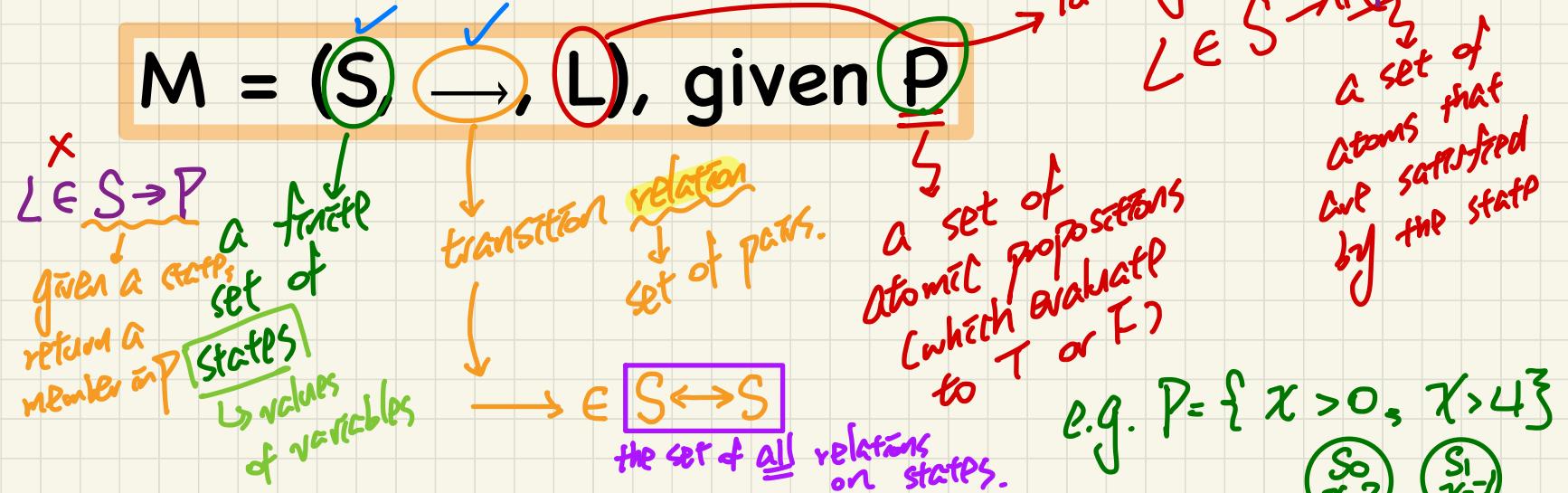
- Lab2 released
- WrittenTest1 coming

↳ cover until and including today

+ some left-over examples

(to be finished within first 20 min
on Thursday).

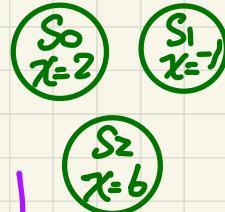
Labelled Transition System (LTS)



Q. Formulate deadlock freedom:

From any state, it is always possible to make progress.

$$\forall s \in S \cdot s \in S \Rightarrow (\exists s' \in S \cdot (s, s') \in \xrightarrow{L}) \quad \times L(s) \neq \emptyset$$



$$\begin{aligned} L(S_0) &= \{x > 0\} \\ L(S_1) &= \{x = 1\} \\ L(S_2) &= \{x > 0\} \end{aligned}$$

Labelled Transition System (LTS)

Exercise

Exercises Consider the system with a counter c with the following assumption:

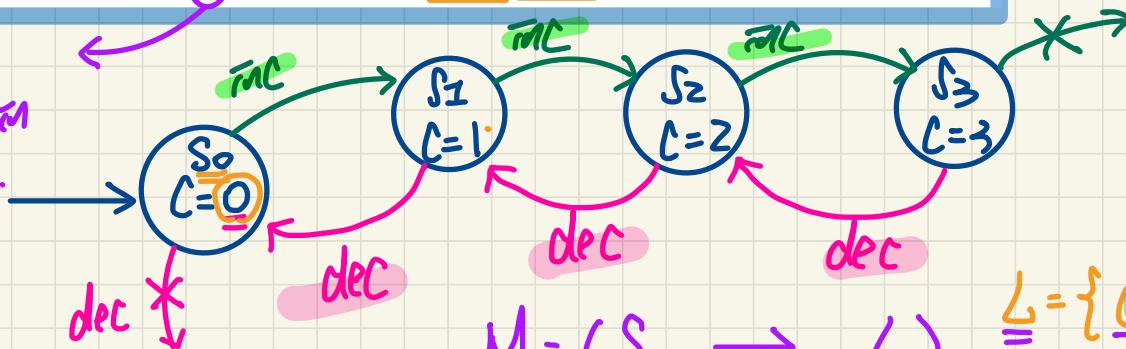
$$0 \leq c \leq 3$$

Say c is initialized 0 and may be incremented (via a transition inc , enabled when $c < 3$) or decremented (via a transition dec , enabled when $c > 0$).

- Draw a **state graph** of this system.
- Formulate the state graph as an **LTS** (via a triple (S, \rightarrow, L)).

Assume: Set P of atoms is: $\{c \geq 1, c \leq 1\}$

properties
that were
interested in
verifying:



$$M = (S, \rightarrow, L)$$

$$(S_3, \{C > 1\})$$

$$\begin{aligned} 0 < C_1 \leq 2 & \quad \text{inc}_1 \\ 3 \leq C_2 \leq 5 & \quad \text{inc}_2 \\ \downarrow \text{init}: C_1 = 1 & \\ C_2 = 3 & \end{aligned}$$

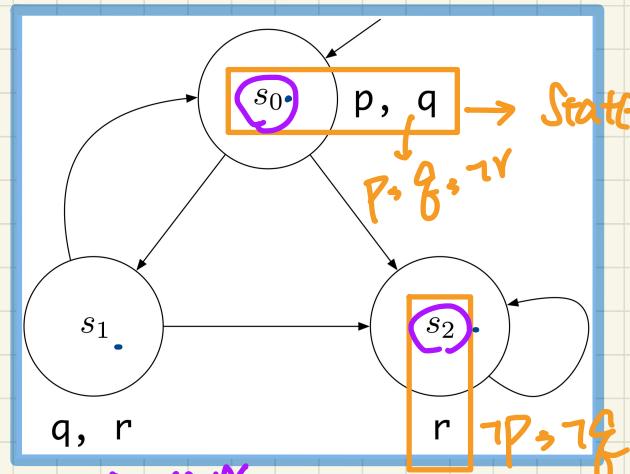
$$\begin{aligned} S = \{S_0, S_1, S_2, S_3\} \\ \rightarrow = \{ \end{aligned}$$

$$\begin{aligned} (S_0, S_1), \\ (S_1, S_2), \\ (S_2, S_3), \\ (S_3, S_2), \\ (S_3, S_1), \\ (S_1, S_0) \} \end{aligned}$$

$$\begin{aligned} \Leftarrow = \{ \end{aligned}$$

$$\begin{aligned} (S_0, \{C \leq 1\}), \\ (S_1, \{C \geq 1, C \leq 1\}), \\ (S_2, \{C > 1\}), \\ (S_3, \{C > 1\}), \end{aligned}$$

Labelled Transition System (LTS): Formulation & Paths



Path: $\pi = \underline{s_0} \xrightarrow{\text{Step names}} \underline{s_1} \xrightarrow{\text{Step names}} \underline{s_2} \xrightarrow{\text{Step names}} \underline{s_2} \rightarrow \dots$

$\underline{s_0} \xrightarrow{\text{Step indices}} \underline{s_1} \xrightarrow{\text{Step indices}} \underline{s_2} \xrightarrow{\text{Step indices}} \underline{s_3} \xrightarrow{\text{Step indices}} \dots$

1st state in path 2nd state in path 3rd state in path indices

Assume: $P = \{P, Q, R\}$

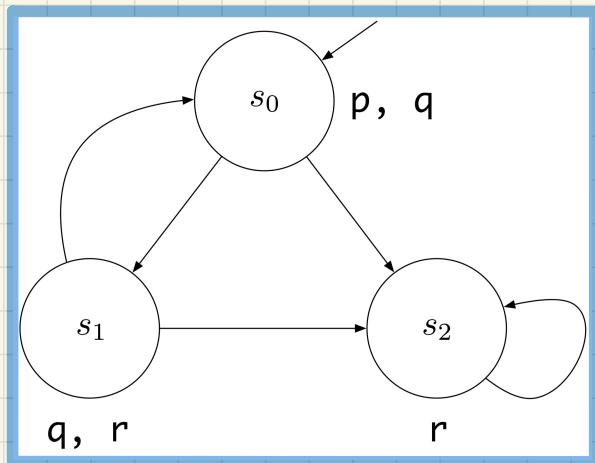
State s_0 satisfies P and Q
(implicitly, R is not satisfied)

$$M = (S, \rightarrow, \angle)$$

$$S = \{s_0, s_1, s_2\}$$

$$\rightarrow = \{(s_0, s_1); (s_0, s_2), (s_1, s_0); (s_1, s_2), (s_2, s_0); (s_2, s_1)\}$$

$$\angle = \{ (s_0, \{P, Q\}), (s_1, \{Q, R\}), (s_2, \{R\}) \}$$



$$\pi^3 = \textcolor{brown}{s_0} \rightarrow \textcolor{brown}{s_1} \rightarrow \textcolor{brown}{s_0} \rightarrow \textcolor{brown}{s_1} \rightarrow \dots$$

$$\pi = \textcolor{brown}{s_1} \rightarrow \textcolor{brown}{s_2} \rightarrow \textcolor{brown}{s_3} \rightarrow \textcolor{brown}{s_4} \rightarrow \textcolor{brown}{s_5} \rightarrow \dots$$

$$\begin{aligned} (\pi^2)^3 &= s_4 \rightarrow s_5 \rightarrow \dots \\ &= \pi^4 \end{aligned}$$

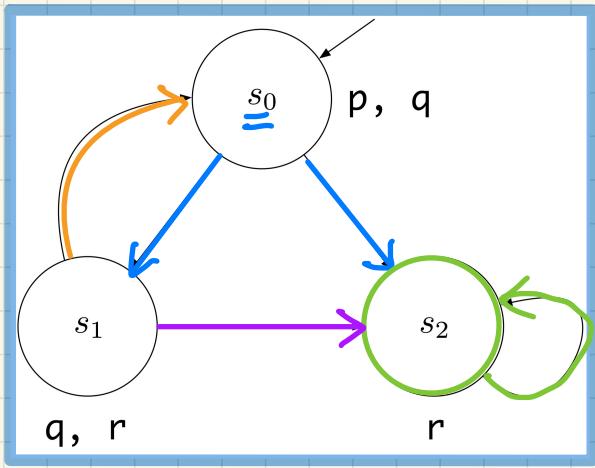
$$\pi = s_0 \rightarrow \textcolor{brown}{s_1} \rightarrow \textcolor{brown}{s_0} \rightarrow \textcolor{brown}{s_1} \rightarrow \textcolor{brown}{s_0} \rightarrow \textcolor{brown}{s_1} \rightarrow \dots$$

Pattern: $s_1 \quad s_2 \quad s_3 \quad s_4 \quad s_5 \quad s_6$

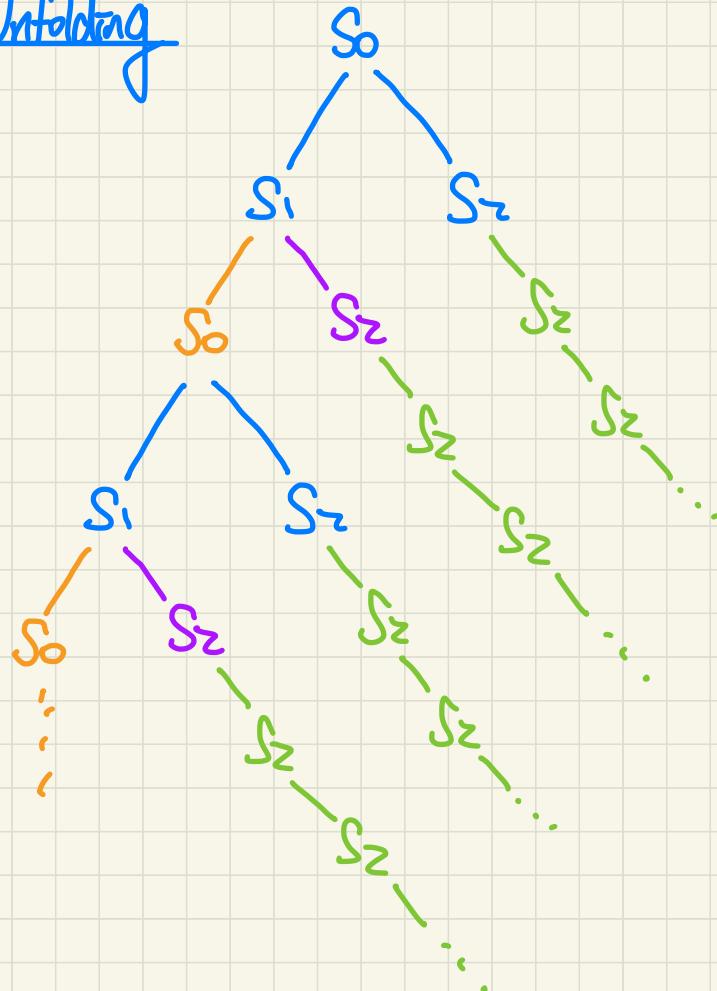
$\times \pi^0$

$$\pi^1 = \pi$$

$$\pi^2 = \textcolor{brown}{s_1} \rightarrow \textcolor{brown}{s_0} \rightarrow \textcolor{brown}{s_1} \rightarrow \textcolor{brown}{s_0} \rightarrow \textcolor{brown}{s_1} \rightarrow \dots$$



Unfolding



Path Satisfaction: Logical Operations

A **path** satisfies a **proposition**

if its **initial state** ("current state") satisfies it.

first step
in TC



$$\Pi \models p \Leftrightarrow p \in \mathcal{L}(s_1)$$

$$\Pi \models T \checkmark \text{ 1st state labelling satisfies } T$$

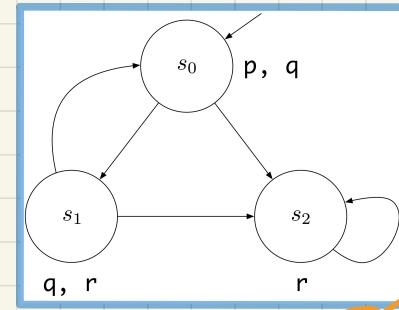
$$\Pi \not\models \perp \Leftrightarrow \neg(\Pi \models \perp)$$

$$\Pi \models \neg\phi \Leftrightarrow \neg(\Pi \models \phi)$$

$$\Pi \models \phi_1 \wedge \phi_2 \Leftrightarrow \Pi \models \phi_1 \wedge \Pi \models \phi_2$$

$$\Pi \models \phi_1 \vee \phi_2$$

$$\Pi \models \phi_1 \Rightarrow \phi_2$$



e.g. $\Pi = s_0 \rightarrow s_2 \rightarrow s_2 \rightarrow \dots$

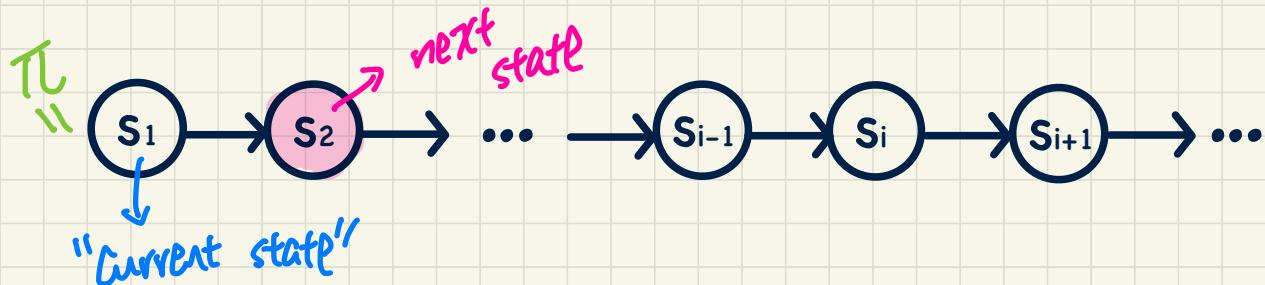
$\Pi \models p$

$\Pi \not\models \perp$

Path Satisfaction: Temporal Operations (1)

A **path** satisfies $X\phi$

if the **next state** (of the "current state") satisfies it.



Formulation (over a path)

$$\pi \models X\phi \Leftrightarrow \pi^2 \models \phi$$

* π^3
Q. What is $\pi^3 \models X p$ checking?

Path Satisfaction: Temporal Operations (2)

A **path** satisfies $G\phi$ ^{Global}

if the every state satisfies it.



Formulation (over a path)

$$\pi \models G\phi \Leftrightarrow \forall i \cdot i \geq 1 \Rightarrow \boxed{\pi^i \models \phi}$$

Path Satisfaction: Temporal Operations (3)

A **path** satisfies $F\phi$ ^{Future}

if some future state satisfies it.



Formulation (over a path)

$$\pi \models F\phi \Leftrightarrow \exists i. i \gg 1 \wedge \boxed{\pi^i \models \phi}$$